

Functional grading of viscoelastic defined hot mix asphalt layers

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Manuscript Code: 13750

Date of Acceptance/Reception: 23.10.2020/10.03.2020

DOI: 10.7764/RDLC.19.3.258

Abstract

In the design of layered flexible pavements with the mechanistic-empirical (M-E) method, the material characterization of layers is critical for the correct calculation of mechanical responses. The surface layers of flexible pavements produced as hot mix asphalt (HMA) behave as a viscoelastic material under real field conditions. In this study, in which the HMA surface layer was defined viscoelastic by creep-compliance method, functional grading was applied to the surface layer at the same time to increase the fatigue strength of the pavement. Functional grading application was performed in the form of 3, 5, 7, and 9 sub-layers with linear and exponential functions. The pavement life values due to the mechanical responses that occurred in the pavement were determined by the Asphalt Institute and Shell methods. The study results show that the fatigue strength of the viscoelastic surface layer increases significantly as a result of functional grading. Especially in sections with exponential grading, an improvement of more than 10% was achieved even when a small number of sub-layers used. These results show that functional grading can also be successfully applied in field studies, and even with three sub-layers, significant improvements can be provided.

Key words: Hot mix asphalt, mechanistic-empirical pavement design, creep-compliance, viscoelastic material, functional grading, fatigue.

Introduction

When flexible pavement layers are subjected to wheel load and environmental influences, critical stress and strains occur at various locations through the depth of the pavement. In the mechanistic-empirical (M-E) design method (Huang, 2004), which is one of the methods used in the design of flexible pavements, these stresses and strains occurring in the pavement are calculated mechanically, and the values obtained are used for the pavement life estimation with the help of empirical transfer functions (Ali, H. A. Tayabji, 1998; Behiry, 2012; Gedafa, 2006; Jeong, 2005; Mousa, Abo-Hashema, Gadallah, & Mousa, 2015).

The two critical distress types used in pavement life estimation are fatigue and rutting. While the maximum compressive strain values occurring on the top of the subgrade are used in the rutting lifetime estimation of the pavement, the tensile strain values occurring under the hot mix asphalt (HMA) surface layer are also used in the fatigue-based pavement life estimate (Aktaş, Aytakin, & Aslan, 2019; Behiry, 2012; Mousa et al., 2015).

In the M-E design method, material identification data are needed to model the pavement layers and to calculate critical stress and strain. Flexible pavements are often modeled as multilayered linear elastic systems. Burmister's elastic layer theory is one of the most practical and common mechanical models used for this purpose. The mechanical parameters needed in this model, in which all layers in the system are considered homogeneous and isotropic, are the elasticity modulus (E) and Poisson's ratio (ν) of the layers (Huang, 2004; Jeong, 2005; Singh & Sahoo, 2020). However, under real field conditions, HMA layers act as a viscoelastic material, and their mechanical responses depend on temperature and loading time (Ahmed & Erlingsson, 2016; Chen, Pan, & Green, 2009; Jeong, 2005; Koohmishi, 2013).

The first of the two basic methods used in the definition of viscoelastic materials are mechanical models in which the elastic behavior of viscoelastic materials is characterized by the spring and the viscous by the dash-pot.

The Maxwell model, in which the spring and dash-pot is connected in series, the Kelvin model in which it is connected in parallel, the Burgers model, is the combination of Maxwell and Kelvin models, and Kelvin-Voigt model are frequently used in the viscoelastic definition of asphalt paving layers (Ambassa, Allou, Petit, & Eko, 2013; Huang, 2004; Mejtn, Judycki, & Dożycki, 2017).

Another common method used to characterize the responses of viscoelastic materials under load is to measure the creep behavior of the material at different temperatures and different loading times (Jeong, 2005). In the creep compliance method preferred because it is simpler than mechanical models, the Poisson's ratio, which has little effect on pavement behavior, is considered elastic and time-independent.

Therefore, only E is considered viscoelastic and time-dependent. Creep compliance (D(t)) value is defined by Equation 1 (Huang, 2004; Safi, Hossain, Wu, Al-Qadi, & Ozer, 2018).

$$D(t) = \frac{\varepsilon(t)}{\sigma} \quad (1)$$

In the equation, $\varepsilon(t)$ refers to the time-dependent strain under constant stress (σ). Accordingly, D(t) is the reciprocal of E under constant stress.

The creep test applied to HMA is an important experiment carried out to determine the strain of the material, both independent of time (elastic) and time-dependent (viscoelastic and plastic). The results obtained from this experiment at low temperatures are used for the prediction of thermal cracking development, and the values obtained at high temperatures are used for the prediction of rutting.

Test methods used to measure the creep behavior of HMA can be listed as, uniaxial, triaxial, and indirect tensile tests. Uniaxial testing is more preferred because it is simple and reflects the in-situ behavior of flexible pavements. The triaxial test also reflects the in-situ conditions well due to the horizontal confinement, but this method cannot be widely used because of the complexity of equipment setting up (Safi et al., 2018).

Indirect tensile test (IDT) that is preferred by the Strategic Highway Research Program (SHRP) characterizes the thermal cracking performance of HMA at low temperatures (Marasteanu et al., 2012; Richardson & Lusher, 2008; Safi et al., 2018). In this experiment, creep compliances of different asphalt concrete mixtures are obtained according to the standard AASHTO T 322-07 method (Christensen & Bonaquist, 2004; Jeong, 2005; Richardson & Lusher, 2008; Safi et al., 2018).

Functionally graded materials (FGMs) are widely used in many different engineering applications, such as shipbuilding, automotive and aerospace industry, civil, nuclear power plants, and medical devices, thanks to their attractive mechanical properties (Miteva, 2014; Xu & Meng, 2018; Zhang & Yang, 2020). The mechanical properties of these materials such as E, ν , shear modulus, and conductivity, show a continuous and gradual change along with one or both directions of the material. This situation increases the mechanical capacity of the material desirably. Combining specific ceramic properties such as high temperature and corrosion resistance and specific metal properties such as high mechanical strength and toughness in a single material are typical examples of functional grading (Ghayesh, 2018; Jin & Paulino, 2002). Smaller stress concentrations, increased thermal properties, high fracture toughness, and reduction of thermal stresses are examples of the benefits of FGMs (Hilton & Lee, 2012).

Functional grading provides a gradual transition from one layer to another, which eliminates the sharp interfaces that the failure begins, and is considered as an alternative to layered composites as well as to homogeneous materials (Ashwinkumar A kokanee, 2017; Mahamood, Akinlabi, Shukla, & Pityana, 2012; Miteva, 2014).

In the functional grading of layered structures, the layers are divided into sub-layers, and their mechanical properties are changed throughout the depth by a certain function or the power-law (Çömez, 2015; Guler & Erdogan, 2004; Liu & Wang, 2008; Liu, Wang, & Zhang, 2008). The usual power law is widely used in the analysis of civil engineering structures such as rods, beams, plates, and shells (Chakraborty, Gopalakrishnan, & Reddy, 2003; Demirbas, 2017; Kahya & Turan, 2017; Xu & Meng, 2018).

Viscoelastic functional graded materials can also be considered as a member of the FGMs family. In viscoelastic functional graded materials, the material properties change not only in a certain direction but also depending on the time (Zhang & Yang, 2020). HMA layers are a good example of materials best suited for viscoelastic grading. The material properties of asphalt pavements vary significantly depending on aging and temperature (Dave, Paulino, & Buttlar, 2011).

Flexible pavements consist of surface, base and, sub-base layers whose mechanical properties are quite different from each other. In this layered structure, the bituminous surface layer exhibits a viscoelastic behavior (Ahmed & Erlingsson, 2016; Mistry & Roy, 2020; Safi et al., 2018), while the granular base and sub-base layers can be characterized as linear elastic or non-linear elastic.

While linear elasticity is accepted as a valid method in relatively thick pavement layers, non-linear characteristics of materials should be considered in thin layers. The most important parameter used in non-linear identification of

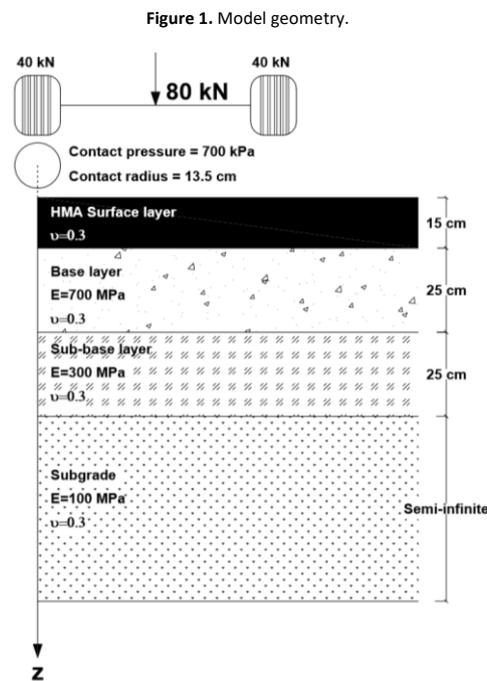
granular layers is the resilient modulus (M_r) (Abd Alla, 2006; Ghadimi & Nikraz, 2017; Ng, Henrichs, Ksaibati, & Wulff, 2018; Titi & Matar, 2018).

In this study, which aims to analyze the pavement life change with the M-E design method as a result of the functional grading of the bituminous surface layer showing viscoelastic behavior, the surface layer divided into 3,5,7 and 9 sub-layers and was graded with linear and exponential functions. Since the main purpose of the study is to examine the effects of viscoelastic functional grading, the granular base and sub-base layers are defined as linear elastic.

It is thought that the study will provide a unique contribution to the studies in the field of pavement engineering in terms of creating an example that is not included in the literature on the functional grading of the viscoelastic layers defined with the creep compliance method and discussing the benefits of this method on pavement

Materials and Methods

Layer thicknesses were defined on the z-axis by selecting a conventional flexible pavement section (Figure 3). The creep compliance method (Huang, 2004) was used for the viscoelastic definition of the surface layer and the time-dependent $D(t)$ values of the HMA layer and the modulus of elasticity at the relevant time ($E(t)$) are given in Table 1. Linear elastic layer parameters (E and ν) of the base, sub-base, and subgrade are shown in Figure 1.



In the mechanical analysis, the axle load on the single axle is determined as 80 kN (8.2 tons), and this load is distributed equally on the wheels (Moreno, Navarro, & Zeballos, 2017). Wheel internal pressure (contact pressure) (CP) was chosen as 700 kPa (Hadi & Bodhinayake, 2003). The contact radius (CR) for the circular wheel contact area providing this internal pressure was calculated as 13.5 cm.

In the analysis, the contact surfaces between the layers are defined as bonded. KENLAYER program was used to determine the stress and strain values. The program has been successfully used to calculate the mechanical responses of linear elastic, non-linear elastic, and viscoelastic defined multilayered flexible pavements under different loading conditions for any chosen depth and lateral distance (Chegenizadeh, Keramatikerman, & Nikraz, 2016; Huang, 2004; Muniandy, Aburkaba, & Thamer, 2013).

For the functional grading process, the viscoelastic HMA layer is divided into sub-layers (3, 5, 7 and 9 sub-layers). Grading was applied according to a certain function, and linear and exponential grading functions were used for this purpose. It is assumed that the $D(t)$ value calculated for the mid-depth of each sub-layer with the related functions represents the entire sub-layer.

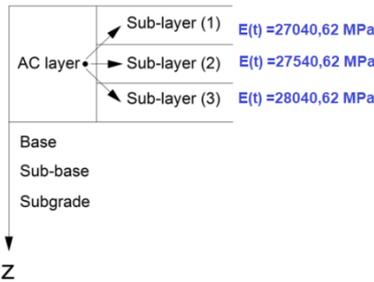
In the use of grading functions, $1/D(t)$ values were used instead of $D(t)$ values to reduce complexity and change the modulus of elasticity ($1/D(t)$) in compliance with a certain rule. Accordingly, calculated $E(t)$ values are converted back to $D(t)$ and entered as viscoelastic material identification data to KENLAYER.

In the linear grading process, the $E(t)$ value at any moment of the middle sub-layer is kept equal to the non-graded $E(t)$ value, and the $E(t)$ values of the other sub-layers have been changed with a certain linear increase or decrease value in the z -axis direction. Increase or decrease values are determined as 100, 250, and 500 MPa. An illustration of this application is given in Figure 2.

Table 1. Time-dependent $D(t)$ and $E(t)$ values (Richardson & Lusher, 2008)

Temperature (°C)	Time (sec)	$D(t)$ (1/GPa)	$E(t)$ (MPa)
-20	1	0.03631	27540,62
	2	0.03720	26881,72
	5	0.03906	25601,64
	10	0.04095	24420,02
	20	0.04225	23668,64
	50	0.04574	21862,7
	100	0.04750	21052,63

Figure 2. Linear grading application with 3 sub-layers and 500 MPa increasing for $t=1$ sec.



In the exponential grading process, the modulus of elasticity ($E(i,t)$) of any sub-layer (i) at the moment (t) is calculated by Equation 2 (Çómez, 2015; Giannakopoulos & Pallot, 2000; Ramirez, Heyliger, & Pan, 2006). In the equation, E_{top} is the modulus of elasticity at the top of the HMA layer, z is mid-depth (m) of the sub-layer from top of the related layer, and μ inhomogeneity coefficient. In this study, this coefficient was taken as 1, -1, 0.5 and -0.5 for different variations.

$$E(i, t) = E_{top} e^{\mu z} \quad (2)$$

In the functional grading process, the average elasticity modulus value (E_{avg}) of the sub-layers was calculated with Equation 3, and this value was provided to be equal to the non-graded layer's elasticity module (Bostancıoğlu, 2019). Thus, the viscoelastic surface layer is neither reinforced nor weakened according to the non-graded situation. Changes in pavement life are associated only with functional grading.

$$E_{avg} = \frac{\sum(E_i d_i)}{\sum d_i} \quad (3)$$

In the equation, E_i denotes the modulus of elasticity and d_i denotes the thickness of any sub-layer (i).

In the M-E design method, mechanical responses (displacement, stress, and strain) must be converted into a parameter that reflects the pavement performance. The most commonly used parameters for this purpose are pavement life values based on the fatigue and rutting failure.

Different models have been proposed by different agencies in the transfer of mechanical responses to pavement life values (Behiry, 2012). The general form of these models is given in Equation 4 and 5, and the coefficients (f_1 - f_5) used in the equations are given in Table 2. In the current study, transfer models of Asphalt Institute (AI) and Shell Research (SR) were taken into consideration.

$$N_f = f_1 \varepsilon_r^{-f_2} E^{-f_3} \quad (4)$$

$$N_r = f4(\varepsilon_v)^{-f5} \quad (5)$$

In the equations, the N_f and N_r indicate the number of load applications to fatigue and rutting failure respectively, ε_r is the horizontal tensile strain at the bottom of the HMA layer, ε_v is the compressive strain on the subgrade and the E_1 is the elasticity modulus (psi) of the HMA layer. E_1 value is used as E_{avg} in sections with functional grading.

Table 2. Model coefficients for different agencies (Behiry, 2012).

	Asphalt Institute	Shell Research	US Army Corps of Engineers	Belgian Road Research Center	Transport and Road Research Laboratory	Federal Highway Administration	ILLINOIS Department of Transportation	Austin Research Engineers
f1	0.0795	0.0685	497.156	4.92E-14	1.66E-10	0.1001	5.00E-06	4.88E-01
f2	3.291	5.671	5	4.76	4.32	3.565	3	3.0312
f3	0.854	2.363	2.66	0	0	1.474	0	0.6529
f4	1.37E-09	6.15E-07	1.81E-15	3.05E-09	1.13E-06	---	---	---
f5	4.477	4	6.527	4.35	3.75	---	---	---

In the study, the non-graded section was defined as the "control section". The coding system used for sections with functional grading is briefly described in Table 3.

Table 3. Coding system

Coding	Description
LG3_100i	Linear Grading, 3 sub-layers, elasticity modulus increases 100 MPa from top to bottom for each sub-layer
LG3_100D	Linear Grading, 3 sub-layers, elasticity modulus decreases 100 MPa from top to bottom for each sub-layer
EG_3_05	Exponential Grading, 3 sub-layers, inhomogeneity coefficient is 0.5
EG_3_M05	Exponential Grading, 3 sub-layers, inhomogeneity coefficient is minus 0.5

Equation 6 was used to determine the change (C (%)) provided by the functional grading process compared to the control section.

$$C(\%) = \frac{N_i - N_{control}}{N_{control}} \times 100 \quad (6)$$

In the equation, N_i represents the calculated N_f or N_r value for any section, $N_{control}$ shows the calculated N_f or N_r value for the control section.

Results and Discussion

As a result of the mechanical analysis for the control section, the strain values occurring under the HMA layer and on the subgrade and the pavement life values calculated based on these values are given in Table 4.

In addition to the control section, 48 functionally graded sections were divided into two groups as sections where E was increased from top to bottom (Group 1) and sections that were decreased (Group 2). The road life and C(%) values calculated according to AI and Shell methods for both groups are given in Tables 5 and 6 for t=1 sec loading time.

When Tables 5 and 6 are analyzed, it is determined that N_f values increase by 7.08% for the AI method and 12.51% for the Shell method in group 1. In this case, although the N_r values have decreased, it is seen that the reduction rates are not excessive. In Group 2 sections, it has been determined that the pavement life due to rutting has increased slightly, but the pavement life values due to fatigue have decreased significantly. According to these values, it is clearly seen that the functions and parameters used in the functional grading contribute more positively to the fatigue life of the road than rutting life.

Table 4. Mechanical analysis results and N_f and N_r values for the control section.

t (sec)	Fatigue parameter		Rutting parameter		Fatigue Life (N_f)		Rutting Life (N_r)	
	ϵ_r (E-05)		ϵ_v (E-04)		AI	Shell	AI	Shell
1	-4,034		1,118		52996590,41	143325907,3	672739011,4	3936478661
2	-4,100		1,127		51290193,57	138422485,5	649018677,3	3812233133
5	-4,233		1,144		48139571,52	129613989,3	606942089,8	3590633000
10	-4,365		1,16		45304257,32	121763251,6	570350923,9	3396590252
20	-4,454		1,171		43539296,05	116916820,1	546753218,1	3270751396
50	-4,685		1,199		39450270,27	105875784,1	491866318,5	2975763300
100	-4,799		1,212		37643635,93	101002476,9	468683147,9	2850129783

This increase in fatigue strength of the pavement can be explained by 2 phenomena.

- i) Strengthening the HMA-base interface through the increase of E from top to bottom,
- ii) The basic parameter used in N_f calculation (Equation 4) is the tensile strain at the HMA-base interface.

Table 5. N_f , N_r and C(%) values for group 1.

Coding	t (sec)	Fatigue Life (N_f)		Rutting Life (N_r)		Fatigue Life (C%)		Rutting Life (C%)	
		AI	Shell	AI	Shell	AI	Shell	AI	Shell
LG3_100i	1	5.317E+07	1.441E+08	6.727E+08	3.936E+09	0.33	0.56	0.00	0.00
LG3_200i	1	5.339E+07	1.452E+08	6.701E+08	3.922E+09	0.74	1.27	-0.40	-0.36
LG3_300i	1	5.361E+07	1.462E+08	6.701E+08	3.922E+09	1.15	1.99	-0.40	-0.36
LG3_500i	1	5.405E+07	1.483E+08	6.674E+08	3.908E+09	1.98	3.44	-0.80	-0.71
LG5_100i	1	5.334E+07	1.449E+08	6.701E+08	3.922E+09	0.66	1.13	-0.40	-0.36
LG5_200i	1	5.374E+07	1.468E+08	6.701E+08	3.922E+09	1.40	2.42	-0.40	-0.36
LG5_300i	1	5.418E+07	1.489E+08	6.674E+08	3.908E+09	2.23	3.88	-0.80	-0.71
LG5_500i	1	5.494E+07	1.525E+08	6.647E+08	3.895E+09	3.68	6.42	-1.19	-1.07
LG7_100i	1	5.356E+07	1.460E+08	6.701E+08	3.922E+09	1.07	1.85	-0.40	-0.36
LG7_200i	1	5.414E+07	1.487E+08	6.701E+08	3.922E+09	2.15	3.73	-0.40	-0.36
LG7_300i	1	5.472E+07	1.514E+08	6.674E+08	3.908E+09	3.25	5.66	-0.80	-0.71
LG7_500i	1	5.586E+07	1.569E+08	6.621E+08	3.881E+09	5.40	9.49	-1.59	-1.42
LG9_100i	1	5.374E+07	1.468E+08	6.701E+08	3.922E+09	1.40	2.42	-0.40	-0.36
LG9_200i	1	5.449E+07	1.504E+08	6.674E+08	3.908E+09	2.82	4.92	-0.80	-0.71
LG9_300i	1	5.526E+07	1.540E+08	6.647E+08	3.895E+09	4.28	7.48	-1.19	-1.07
LG9_500i	1	5.675E+07	1.613E+08	6.594E+08	3.867E+09	7.08	12.51	-1.98	-1.77
EG_3_05	1	5.449E+07	1.504E+08	6.674E+08	3.908E+09	2.82	4.92	-0.80	-0.71
EG_3_1	1	5.605E+07	1.578E+08	6.621E+08	3.881E+09	5.75	10.12	-1.59	-1.42
EG_5_05	1	5.467E+07	1.512E+08	6.674E+08	3.908E+09	3.16	5.51	-0.80	-0.71
EG_5_1	1	5.642E+07	1.596E+08	6.621E+08	3.881E+09	6.46	11.39	-1.59	-1.42
E_G_7_05	1	5.472E+07	1.514E+08	6.674E+08	3.908E+09	3.25	5.66	-0.80	-0.71
EG_7_1	1	5.656E+07	1.603E+08	6.621E+08	3.881E+09	6.73	11.87	-1.59	-1.42
E_G_9_05	1	5.476E+07	1.517E+08	6.674E+08	3.908E+09	3.33	5.81	-0.80	-0.71
EG_9_1	1	5.666E+07	1.608E+08	6.621E+08	3.881E+09	6.90	12.19	-1.59	-1.42

When the graphs (Figures 3 and 4) drawn for t=1 sec are examined to determine the effect of the functions and the parameters used in the process of functional grading on the C(%) values; It is observed that the C(%) values increase as the number of sub-layers increases between the sections graded with the linear grading function. According to the Shell method, the highest C(%) value calculated with 3 sub-layers was 3.44, while the C(%) values for 5,7, and 9 sub-layers were 6.42, 9.49 and 12.51, respectively.

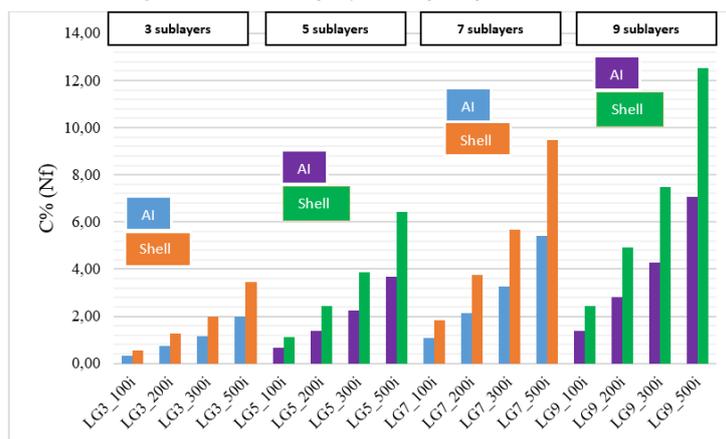
In the examination made between the sections with the same sub-layer number, the C(%) values increased as the stiffness increase value in the z-direction increased. The increase in the stiffness between the sub-layers from 100 MPa to 500 MPa, increased the C(%) values calculated according to the Shell method by 6.14, 5.68, 5.13, and 5.17 times for

the 3,5,7, and 9 sub-layers, respectively, compared to the control section. According to these results, it can be said that the stiffness increase amount is a more effective parameter for the sections with less sub-layer.

Table 6. N_f , N_r and $C(\%)$ values for group 2.

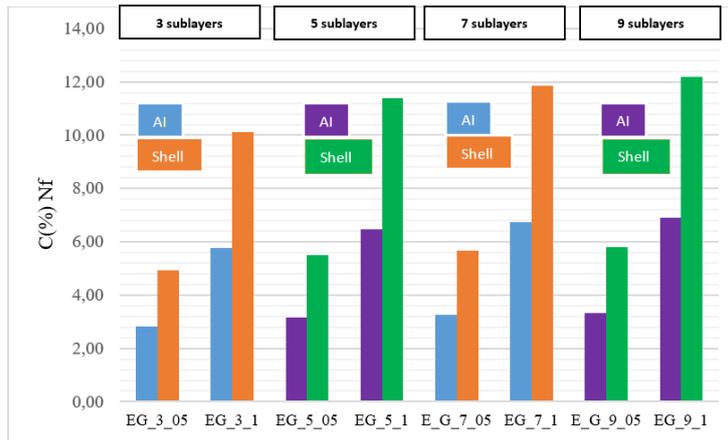
Coding	t (sec)	Fatigue Life (N_f)		Rutting Life (N_r)		Fatigue Life ($C\%$)		Rutting Life ($C\%$)	
		AI	Shell	AI	Shell	AI	Shell	AI	Shell
LG3_100D	1	5.274E+07	1.421E+08	6.727E+08	3.936E+09	-0.49	-0.84	0.00	0.00
LG3_200D	1	5.252E+07	1.411E+08	6.727E+08	3.936E+09	-0.89	-1.53	0.00	0.00
LG3_300D	1	5.231E+07	1.401E+08	6.754E+08	3.951E+09	-1.29	-2.22	0.40	0.36
LG3_500D	1	5.185E+07	1.380E+08	6.754E+08	3.951E+09	-2.17	-3.71	0.40	0.36
LG5_100D	1	5.252E+07	1.411E+08	6.727E+08	3.936E+09	-0.89	-1.53	0.00	0.00
LG5_200D	1	5.214E+07	1.394E+08	6.754E+08	3.951E+09	-1.61	-2.77	0.40	0.36
LG5_300D	1	5.172E+07	1.374E+08	6.754E+08	3.951E+09	-2.41	-4.11	0.40	0.36
LG5_500D	1	5.093E+07	1.338E+08	6.782E+08	3.965E+09	-3.90	-6.62	0.80	0.72
LG7_100D	1	5.240E+07	1.405E+08	6.754E+08	3.951E+09	-1.13	-1.95	0.40	0.36
LG7_200D	1	5.180E+07	1.378E+08	6.754E+08	3.951E+09	-2.25	-3.85	0.40	0.36
LG7_300D	1	5.122E+07	1.351E+08	6.782E+08	3.965E+09	-3.35	-5.70	0.80	0.72
LG7_500D	1	5.004E+07	1.298E+08	6.809E+08	3.979E+09	-5.58	-9.42	1.21	1.08
LG9_100D	1	5.223E+07	1.398E+08	6.754E+08	3.951E+09	-1.45	-2.49	0.40	0.36
LG9_200D	1	5.147E+07	1.363E+08	6.782E+08	3.965E+09	-2.88	-4.91	0.80	0.72
LG9_300D	1	5.069E+07	1.327E+08	6.809E+08	3.979E+09	-4.36	-7.39	1.21	1.08
LG9_500D	1	4.917E+07	1.259E+08	6.836E+08	3.993E+09	-7.23	-12.13	1.62	1.44
EG_3_M05	1	5.147E+07	1.363E+08	6.782E+08	3.965E+09	-2.88	-4.91	0.80	0.72
EG_3_M1	1	5.004E+07	1.298E+08	6.836E+08	3.993E+09	-5.58	-9.42	1.62	1.44
EG_5_M05	1	5.130E+07	1.355E+08	6.782E+08	3.965E+09	-3.20	-5.44	0.80	0.72
EG_5_M1	1	4.976E+07	1.286E+08	6.836E+08	3.993E+09	-6.11	-10.29	1.62	1.44
E_G_7_M05	1	5.126E+07	1.353E+08	6.782E+08	3.965E+09	-3.27	-5.57	0.80	0.72
EG_7_M1	1	4.968E+07	1.282E+08	6.836E+08	3.993E+09	-6.26	-10.54	1.62	1.44
E_G_9_M05	1	5.130E+07	1.355E+08	6.782E+08	3.965E+09	-3.20	-5.44	0.80	0.72
EG_9_M1	1	4.964E+07	1.280E+08	6.836E+08	3.993E+09	-6.33	-10.66	1.62	1.44

Figure 3. $C(\%)$ values for group 1 linear grading sections (t=1 sec).



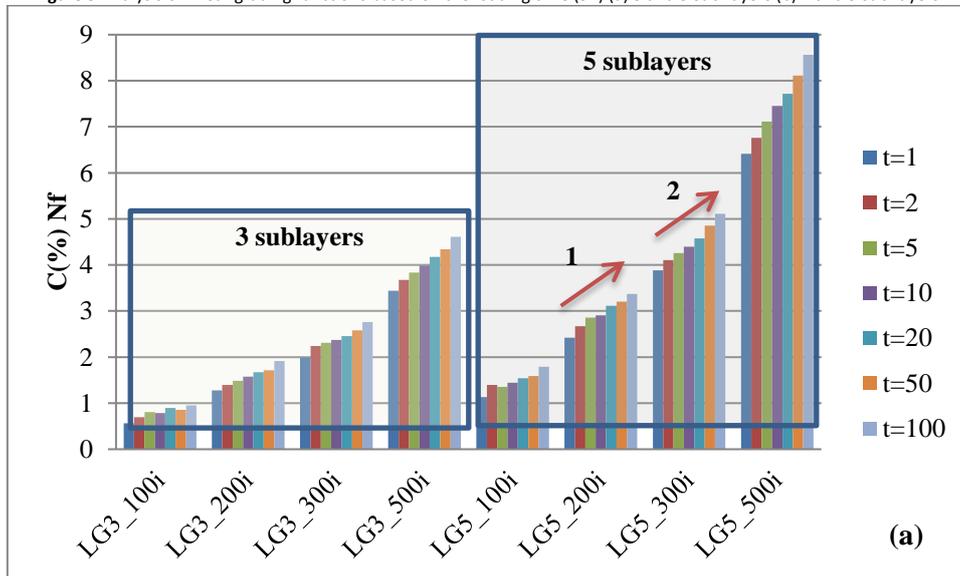
When the Figure 4 showing the $C(\%)$ values at the time of $t=1$ sec for the exponential grading sections, it is seen that the $C(\%)$ values increase due to the increase in the number of sub-layers. However, this increasing rate is much lower compared to linear grading sections. It is observed that the increase of the inhomogeneity coefficient from 0.5 to 1 for exponential grading sections with the same sub-layer number increases fatigue strength.

Figure 4. C(%) values for group 1 exponential grading sections (t=1 sec).



When Figures 5 and 6, in which C(%) values are evaluated together depending on the number of sub-layer, stiffness, and loading time, the positive effect of the increase in all these parameters is seen for linear grading sections. However, no explicit change was observed in the exponential grading sections due to the increase in loading time. C(%) values increased due to the increase in loading time for all sections with the same sub-layer number in sections with linear grading (Figure 5; Row 1 and 2 for 5 sub-layers; Row 3 and 4 for 7 sub-layers). C(%) values increased due to the increase in loading time for all sections with the same sub-layer number in sections with linear grading. No significant C(%) increase was observed in exponential grading sections due to increasing time. However, the C(%) values obtained for all loading time values in these sections are already close to the levels of t=50 sec and t=100 sec in the linear grading sections. For example, for t=50 sec and t=100 sec loading times in LG7_500i section, C(%) values are 11.90 and 12.41 respectively, for t = 1, 2, 5, 10, 20, 50 and 100 sec in EG_7_1 section with the same sub-layer number, the values were obtained as 11.87, 12.14, 12.04, 11.95, 11.98, 11.77 and 11.87, respectively. In other words, while linear grading sections are more effective at long loading times, the exponential grading shows similar efficiency at all loading times.

Figure 5. Analysis of linear grading functions based on the loading time (SR) (a) 3 and 5 sub-layers (b) 7 and 9 sub-layers.



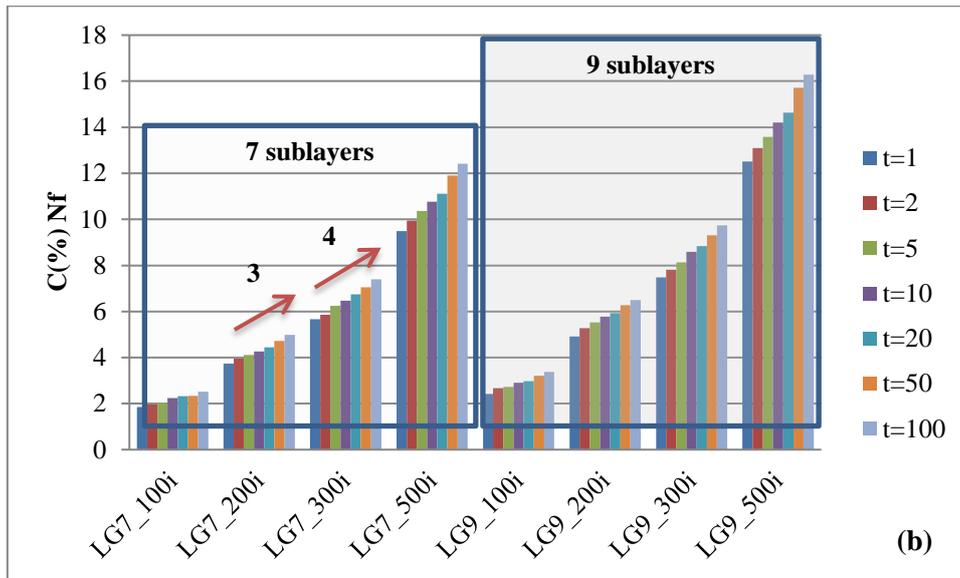
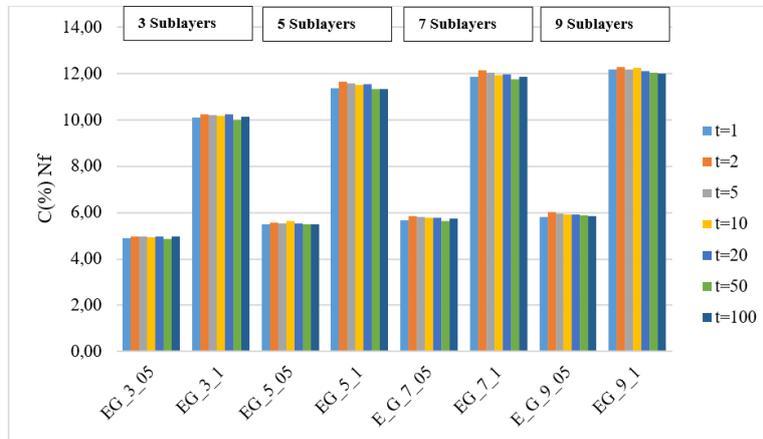


Figure 6. Analysis of exponential grading functions based on the loading time (SR).



For $t=1$ sec, the comparison of linear and exponential grading functions based on the number of sub-layer is given in Figure 7.

When Figure 7 is examined, it is seen that the exponential grading provides higher $C(\%)$ values with fewer sub-layer numbers. The number of sub-layers providing the $C(\%)$ value to be 10 (shown in dashed lines in Figure 9) is calculated as 7.37 for the linear grading and 2.78 for the exponential grading according to the graphic equations. According to these results, it can be said that exponential grading, which provides higher recovery with the less sub-layer number, is an effective method in increasing the fatigue strength and life of flexible pavements.

To determine the efficiency of functional grading under increasing load (loading radius) and loading time conditions, mechanical analyses were performed using different loading times and contact radii. In these analyses, the sections EG_3_1, EG_5_1, LG3_500i, and LG5_500i were used which are thought to be more feasible in field studies because of fewer sub-layers. $C(\%)$ values obtained are given in Figure 8-11.

When Figure 8 is examined, $C(\%)$ values increased for all loading times due to CR increase for section EG_3_1. Accordingly, it can be said that the exponential grading performs well due to the increase in axle load and loading radius. When the effect of loading time on the EG_3_1 section is evaluated, no net increase or decrease was detected. In the graph, the points where $C(\%)$ is maximally determined are 10.56 for $t=5$ sec and $CR=15.5$ cm and 10.54 for $t=2$ sec and $CR=14.5$ cm.

Figure 7. Comparison of linear and exponential graded sections depending on the number of sub-layers (for t=1 sec) (SR).

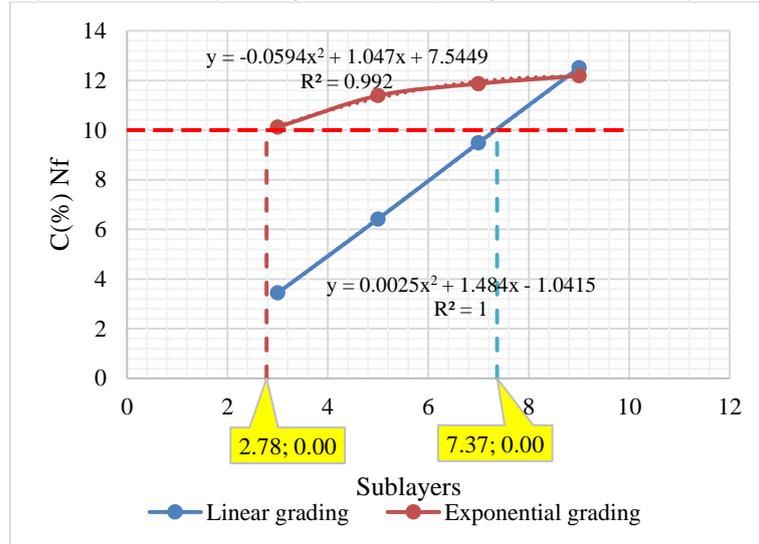


Figure 8. Contact radius and loading time analysis for section EG_3_1 (SR).

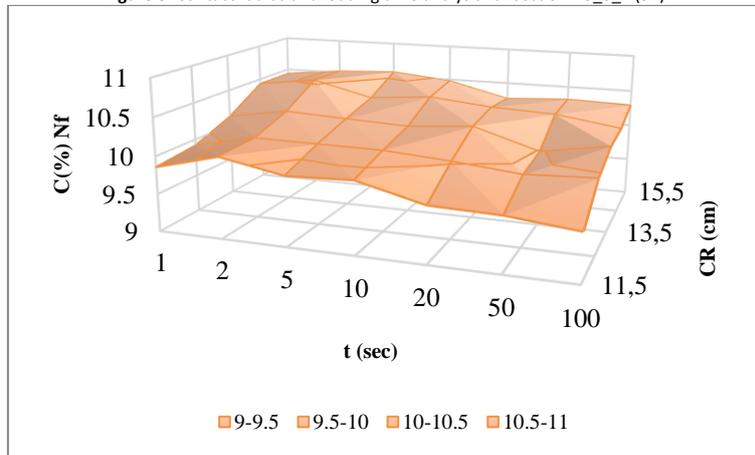
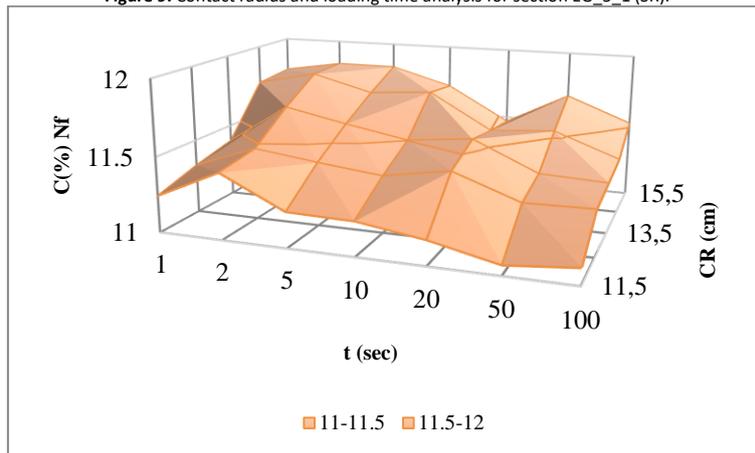


Figure 9. Contact radius and loading time analysis for section EG_5_1 (SR).



When Figure 9 is analyzed, C(%) values increased for all loading times due to the increase in loading radius in section EG_5_1. As in section EG_3_1, the highest C(%) values were obtained for t=2 sec and t=5 sec. The highest C(%) values were determined as 11.83 for t=2 and 5 sec and CR=15.5 cm. According to these values, the number of sub-layers increased from 3 to 5, increasing the C(%) value from 10.56 to 11.83. Depending on the load time change, no significant result was obtained as in section EG_3_1.

Figure 10. Contact radius and loading time analysis for section LG3_500i (SR).

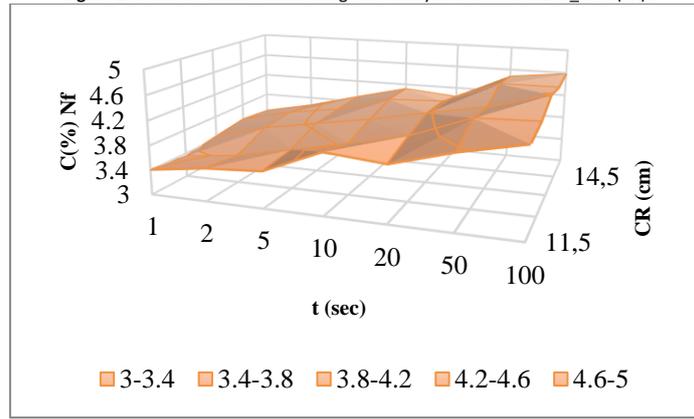
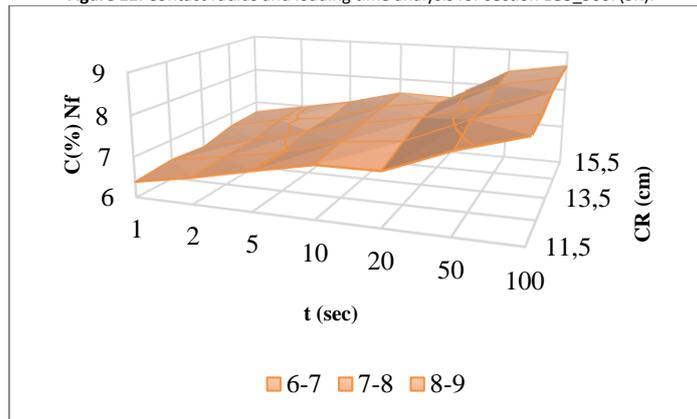


Figure 11. Contact radius and loading time analysis for section LG5_500i (SR).



When figures 10 and 11 are evaluated together, it is seen for all loading radii that the C(%) values increase as loading time increases in linear graded sections. Depending on the loading radius, no significant change was detected in both sections.

Combinations with the highest C(%) values were determined as t=100 sec and CR=13.5 cm for the section LG_3_500i and t=100 sec and CR=13.5 cm for the section LG_5_500i (C% = 8.64). It is seen that these values obtained by linear grading are lower than those obtained in exponentially graded sections with the same sub-layer number.

Another method that can be used to express the axle load increase in the flexible pavements is to increase contact pressure in the same loading radius. Graphs showing the C(%) change depending on the contact pressure change for the EG_3_1 and LG3_500i sections are given in Figures 12 and 13. When the figures 12 and 13 are examined, a meaningful C(%) change due to contact pressure change was not detected in the sections with exponential grading. In the section with linear grading, it can be said that C(%) values do not show excessive change and remain almost constant. Accordingly, it can be said that the functional grading process makes a contribution independent of the contact pressure.

Figure 12. C(%) values due to contact pressure for section EG_3_1 (SR).

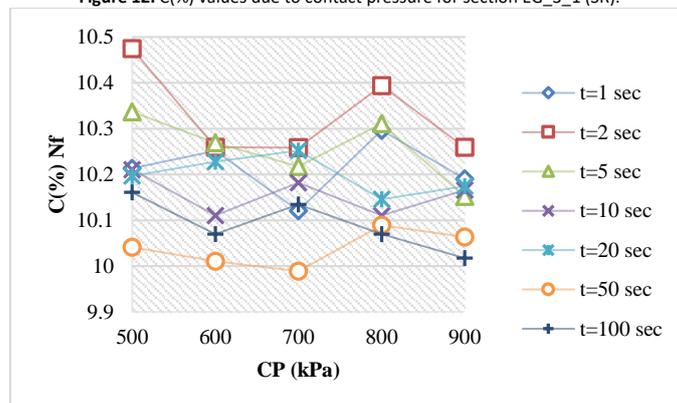
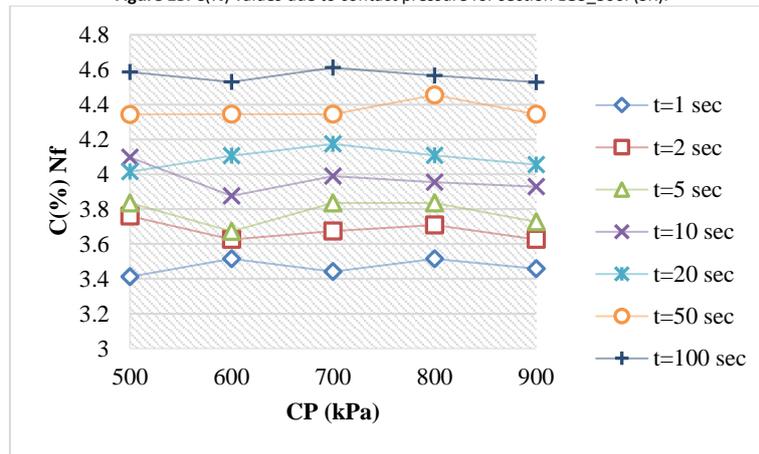


Figure 13. C(%) values due to contact pressure for section LG3_500i (SR).



Conclusions

When the findings obtained from this study, where the viscoelastic defined HMA layer is graded with linear and exponential functions and analyzed mechanically, the following conclusions can be reached;

- Functional grading is a method that can be applied successfully to improve the mechanical properties of viscoelastic defined materials. Thanks to this method, the pavement life values can be significantly increased against deterioration, such as fatigue and rutting. In the functional grading system, there is no additional cost theoretically for the improvement achieved because of the average stiffness of the relevant layer does not change. Therefore, functional grading is a more advantageous method than methods in which the performance of flexible pavements is increased by additives.
- The main type of deterioration to which the pavement is subjected should be analyzed well when performing functional grading. The direction of stiffness increase or decrease of the sub-layers should be chosen according to this critical deterioration type. While fatigue strength improves in applications where stiffness is increased from top to bottom, rutting strength improves in applications where it decreases.
- The number of sub-layer is an important parameter affecting the result in the functional grading method. As the number of sub-layers increases, the deterioration resistance of the pavement increases. However, in real field applications, it is unrealistic to divide an HMA layer into multiple sub-layers (7 or 9 sub-layers). But, in the field applications of HMA, three sub-layers are already applied as surface, binder, and bituminous base. Accordingly, 3 or 5 sub-layers can be practiced easily in the field.
- To briefly summarize the results obtained from the study; As a result of the functional grading of the viscoelastic AC layer with increased rigidity in the z-direction, an increase in fatigue strength reaching 16.3% has been achieved. Increased number of sub-layers in both linear and exponential grading functions increased fatigue strength, but exponential grading function yielded more effective results even with fewer sub-layers. The increase in the $E(t)$ value in the linear grading process and the increase in the inhomogeneity coefficient in the exponential grading process increased the pavement life due to fatigue. In the analyzes based on loading time, the linear grading function gave better results as the loading time increased, while the exponential grading function was not significantly affected by the loading time. It can be said that the exponential grading function provides a higher pavement life value under increasing load and contact radius conditions.
- In the current study, creep compliance values were used for only one temperature value. The functional grading approach can be applied with creep compliance values at different temperatures and for increasing the rutting resistance. Also, more than one layer can be graded functionally rather than just grading the AC layer. Thus, the approach of strengthening more cross sections can be proposed for future studies in this area.

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